# Low－Cost，144MHz，Dual／Triple Op Amps with $\pm 15 k V$ ESD Protection 

## General Description

The MAX4030E／MAX4031E unity－gain stable op amps combine high－speed performance，rail－to－rail outputs， and $\pm 15 \mathrm{kV}$ ESD protection．Targeted for applications where an input or an output is exposed to the outside world，such as video and communications，these devices are compliant with International ESD Standards：$\pm 15 \mathrm{kV}$ IEC 1000－4－2 Air－Gap Discharge， $\pm 8 \mathrm{kV}$ IEC 1000－4－2 Contact Discharge，and the $\pm 15 \mathrm{kV}$ Human Body Model．
The MAX4030E／MAX4031E operate from a single 5V supply and consume only 12 mA of quiescent supply current per amplifier while achieving a $144 \mathrm{MHz}-3 \mathrm{~dB}$ bandwidth， 20 MHz 0.1 dB gain flatness，and a $115 \mathrm{~V} / \mu \mathrm{s}$ slew rate．The MAX4031E provides individual shutdown control for each of the amplifiers．
The dual MAX4030E is available in 8－pin $\mu$ MAX and SO packages，and the triple MAX4031E is available in 14－ pin TSSOP and SO packages．All devices are specified over the $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ extended temperature range．

## Applications

Set－Top Boxes
Standard Definition
Television（SDTV）
Enhanced Television （ETV）
High－Definition Television（HDTV）

Notebooks
Projectors
Security Video Systems
Camcorders
Digital Still Cameras Portable DVD Players


Ordering Information

| PART | TEMP RANGE | PIN－PACKAGE |
| :--- | :--- | :--- |
| MAX4030EEUA | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | $8 \mu \mathrm{MAX}$ |
| MAX4030EESA | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | 8 SO |
| MAX4031EEUD | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | 14 TSSOP |
| MAX4031EESD | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | 14 SO |

Typical Operating Circuit


## Low-Cost, 144MHz, Dual/Triple Op Amps with $\pm 15 k V$ ESD Protection

## ABSOLUTE MAXIMUM RATINGS

(All voltages referenced to GND, unless otherwise noted.)
VCC. $\qquad$
IN_-, IN_+, OUT_, SHDN_ $\qquad$ -0.3 V to $\left(\mathrm{V}_{\mathrm{CC}}+0.3 \mathrm{~V}\right)$
Current into IN_-, IN_+, SHDN. $\qquad$ $\ldots . . . . . . . . . . . . . . \pm 20 \mathrm{~mA}$
Output Short-Circuit Duration to VCC or GND ................................................... Continuous Power Dissipation ( $\mathrm{T}_{\mathrm{A}}=+70^{\circ} \mathrm{C}$ ) $\qquad$ 8-Pin $\mu$ MAX (derate $4.5 \mathrm{~mW} /{ }^{\circ} \mathrm{C}$ above $+70^{\circ} \mathrm{C}$ ) .362 mW
8 -Pin SO (derate $5.9 \mathrm{~mW} /{ }^{\circ} \mathrm{C}$ above $+70^{\circ} \mathrm{C}$ ) .471 mW

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

## DC ELECTRICAL CHARACTERISTICS

$\left(V_{C C}=5 \mathrm{~V}, \mathrm{~V}_{C M}=0 \mathrm{~V}\right.$, $\mathrm{VOUT}_{-}=\mathrm{V}_{C C} / 2, \overline{S H D N_{-}}=\mathrm{V}_{C C}, R_{L}=\infty$ to $\mathrm{V}_{C C} / 2, T_{A}=T_{M I N}$ to $T_{M A X}$, unless otherwise noted. Typical values are at $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$.) (Note 1)


## Low-Cost, 144MHz, Dual/Triple Op Amps with $\pm 15 k V$ ESD Protection

## DC ELECTRICAL CHARACTERISTICS (continued)

$\left(\mathrm{V}_{C C}=5 \mathrm{~V}, \mathrm{~V}_{C M}=0 \mathrm{~V}, \mathrm{~V}_{O U T}=\mathrm{V}_{C C} / 2, \overline{S H D N_{-}}=\mathrm{V}_{C C}, R_{L}=\infty\right.$ to $\mathrm{V}_{C C} / 2, T_{A}=T_{M I N}$ to $T_{M A X}$, unless otherwise noted. Typical values are at $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$.) (Note 1)

| PARAMETER | SYMBOL | CONDITIONS | MIN TYP | MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Disabled Output Leakage Current | Iout_SH | $\overline{\text { SHDN_ }}=$ GND (MAX4031E) | 0.1 | 10 | $\mu \mathrm{A}$ |
| ESD Protection Voltage (Note 2) |  | Human Body Model | $\pm 15$ |  | kV |
|  |  | IEC 1000-4-2 Contact Discharge | $\pm 8$ |  |  |
|  |  | IEC 1000-4-2 Air-Gap Discharge | $\pm 15$ |  |  |

## AC ELECTRICAL CHARACTERISTICS

$\left(V_{C C}=5 \mathrm{~V}, \mathrm{~V}_{C M}=1.5 \mathrm{~V}, \mathrm{R}_{\mathrm{L}}=150 \Omega\right.$ to $\mathrm{GND}, \overline{\mathrm{SHDN}}=\mathrm{V}_{C C}, \mathrm{AVCL}_{-}=+2 \mathrm{~V} / \mathrm{V}, \mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$, unless otherwise noted.)

| PARAMETER | SYMBOL | CONDITIONS | MIN TYP | MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Small-Signal -3dB Bandwidth | BWSS | $\mathrm{V}_{\text {OUT }}=100 \mathrm{mV} \mathrm{P}_{-\mathrm{P}}$, AvCL $=+1 \mathrm{~V} / \mathrm{V}$ | 144 |  | MHz |
|  |  | $\mathrm{V}_{\text {OUT_ }}=100 \mathrm{mV} \mathrm{P}_{- \text {P, }}$, AvCL $=+2 \mathrm{~V} / \mathrm{V}$ | 53 |  |  |
| Large-Signal -3dB Bandwidth | BWLS | Vout_ $=2 \mathrm{VP-P}, \mathrm{AVCL}^{\text {a }}$ + $1 \mathrm{~V} / \mathrm{N}$ | 52 |  | MHz |
|  |  | Vout_ $=2 \mathrm{~V}_{\text {P-P, }}$ AVCL $=+2 \mathrm{~V} / \mathrm{V}$ | 40 |  |  |
| Small-Signal 0.1dB Gain Flatness | BW0.1dBSS | $\mathrm{V}_{\text {OUT_ }}=100 \mathrm{mV} \mathrm{P}_{-\mathrm{P},}$ AvCL $=+1 \mathrm{~V} / \mathrm{V}$ | 20 |  | MHz |
|  |  | $V_{\text {OUT_ }}=100 \mathrm{mV} \mathrm{P}_{-\mathrm{P},}$, AvCL $=+2 \mathrm{~V} / \mathrm{V}$ | 10 |  |  |
| Large-Signal 0.1dB Gain Flatness | BW0.1dBLS | $\mathrm{V}_{\text {OUT }}=2 \mathrm{VPP}_{\text {P-P, }} \mathrm{AVCL}^{\text {a }}$ + $1 \mathrm{~V} / \mathrm{V}$ | 20 |  | MHz |
|  |  | Vout_ $=2 \mathrm{~V}_{\text {P-P, }}$ AVCL $=+2 \mathrm{~V} / \mathrm{V}$ | 9 |  |  |
| Slew Rate | SR | Vout_ = 2 V step | 15 |  | V/us |
| Settling Time to 0.1\% | ts | Vout_ = 2V step | 40 |  | ns |
| Channel-to-Channel Isolation | $\mathrm{CH}_{\text {ISO }}$ | $\mathrm{f}=4.43 \mathrm{MHz}$ | 65 |  | dB |
| Differential Phase Error | DP | NTSC, RL $=150 \Omega$ to GND, AvCL $=+2 \mathrm{~V} / \mathrm{V}$ | 0.2 |  | Degrees |
| Differential Gain Error | DG | NTSC, RL $=150 \Omega$ to GND, AvCL $=+2 \mathrm{~V} / \mathrm{V}$ | 0.2 |  | \% |
| Input Capacitance | CIN |  | 8 |  | pF |
| Capacitive-Load Stability |  | No sustained oscillations | 200 |  | pF |
| Output Impedance | ZOUT | $\mathrm{f}=4.43 \mathrm{MHz}$ | 2 |  | $\Omega$ |
| Enable Time | ton | $\mathrm{V}_{1 \mathrm{~N}_{-}}=1 \mathrm{~V}$ (MAX4031E) | 2 |  | $\mu \mathrm{s}$ |
| Disable Time | toff | $\mathrm{VIN}_{-}=1 \mathrm{~V}$ (MAX4031E) | 0.15 |  | $\mu \mathrm{s}$ |

Note 1: All devices are $100 \%$ production tested at $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$. Specifications over temperature limits are guaranteed by design.
Note 2: ESD protection is specified for test point A and test point B only (Figure 7).

## Low-Cost, 144MHz, Dual/Triple Op Amps with $\pm 15 k V$ ESD Protection

```
(VCC = 5V, VCM = 1.5V, AVCL= +2V/V, RL= 150\Omega to VCC/2, TA = +25*'C, unless otherwise noted.)
```



LARGE-SIGNAL GAIN FLATNESS




LARGE-SIGNAL GAIN vs. FREQUENCY

OUTPUT IMPEDANCE vs. FREQUENCY


COMMON-MODE REJECTION
vs. FREQUENCY


SMALL-SIGNAL GAIN FLATNESS
vs. FREQUENCY


DISTORTION vs. FREQUENCY


POWER-SUPPLY REJECTION vs. FREQUENCY


# Low-Cost, 144MHz, Dual/Triple Op Amps with $\pm 15 k V$ ESD Protection 

Typical Operating Characteristics (continued)
$\left(V_{C C}=5 \mathrm{~V}, \mathrm{~V}_{\mathrm{CM}}=1.5 \mathrm{~V}, \mathrm{AVCL}^{2}=+2 \mathrm{~V} / \mathrm{V}, \mathrm{R}_{\mathrm{L}}=150 \Omega\right.$ to $\mathrm{V}_{\mathrm{C}} / 2, \mathrm{~T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$, unless otherwise noted. $)$


SMALL-SIGNAL PULSE RESPONSE


LARGE-SIGNAL PULSE RESPONSE


ISOLATION RESISTANCE
vs. CAPACITIVE LOAD


CROSSTALK vs. FREQUENCY


## Low-Cost, 144MHz, Dual/Triple Op Amps with $\pm 15 k V$ ESD Protection

Pin Description

| PIN |  | NAME | FUNCTION |  |
| :---: | :---: | :---: | :--- | :---: |
| MAX4030E | MAX4031E |  |  |  |
| 1 | 7 | OUTA | Amplifier A Output |  |
| 2 | 6 | INA- | Amplifier A Inverting Input |  |
| 3 | 5 | INA+ | Amplifier A Noninverting Input |  |
| 4 | 11 | GND | Ground |  |
| 5 | 10 | INB+ | Amplifier B Noninverting Input |  |
| 6 | 9 | INB- | Amplifier B Inverting Input |  |
| 7 | 8 | OUTB | Amplifier B Output |  |
| 8 | 4 | VCC | Positive Power Supply. Bypass VCC to GND with a 0.1 1 F capacitor. |  |
| - | 1 | $\overline{\text { SHDNA }}$ | Amplifier A Shutdown Input. Connect SHDNA high to enable amplifier A. |  |
| - | 2 | $\overline{\text { SHDNC }}$ | Amplifier C Shutdown Input. Connect $\overline{\text { SHDNC }}$ high to enable amplifier C. |  |
| - | 3 | $\overline{\text { SHDNB }}$ | Amplifier B Shutdown Input. Connect $\overline{\text { SHDNB high to enable amplifier B. }}$ |  |
| - | 12 | INC+ | Amplifier C Noninverting Input |  |
| - | 13 | INC- | Amplifier C Inverting Input |  |
| - | 14 | OUTC | Amplifier C Output |  |

## Detailed Description

The MAX4030E/MAX4031E dual/triple, 5V operational amplifiers achieve $115 \mathrm{~V} / \mu$ s slew rates and 144 MHz bandwidths. High $\pm 15 \mathrm{kV}$ ESD protection at video inputs and outputs guards against unexpected discharge. Excellent harmonic distortion and differential gain/ phase performance make these amplifiers an ideal choice for a wide variety of video and RF signal-processing applications.

## Ground-Sensing Inputs

The MAX4030E/MAX4031E input stage can sense com-mon-mode voltages from ground to within 2.25 V of the positive supply.

## Rail-to-Rail Outputs

The MAX4030E/MAX4031E rail-to-rail outputs can swing to within 100 mV of each supply because local feedback around the output stage ensures low openloop output impedance, reducing gain sensitivity to load variations.

## Shutdown (MAX4031E Only)

The MAX4031E offers individual shutdown control for each amplifier. Drive SHDN_ Iow to shut down the amplifier. In shutdown, the amplifier output impedance is high impedance.

## Applications Information

## Choosing Resistor Values

## Unity-Gain Configuration

The MAX4030E/MAX4031E are internally compensated for unity gain. When configured for unity gain, a $24 \Omega$ resistor (RF) in series with the feedback path optimizes AC performance. This resistor improves AC response by reducing the $Q$ of the parallel LC circuit formed by the parasitic feedback capacitance and lead inductance.

## Video Line Driver

The MAX4030E/MAX4031E are low-power, voltagefeedback amplifiers featuring bandwidths up to 40 MHz and 0.1 dB gain flatness to 9 MHz . They are designed to minimize differential-gain error and differential-phase error to $0.2 \%$ and $0.2^{\circ}$, respectively. They have a 40 ns settling time to $0.1 \%, 110 \mathrm{~V} / \mathrm{hs}$ slew rates, and output-current-drive capability of up to 50 mA , making them ideal for driving video loads.

## Inverting and Noninverting Configurations

Select the feedback ( $\mathrm{RF}_{\mathrm{F}}$ ) and input ( $\mathrm{R}_{\mathrm{G}}$ ) resistor values to fit the gain requirements of the application. Large resistor values increase voltage noise and interact with the amplifier's input and PC board capacitance. This can generate undesirable poles and zeros and

## Low－Cost，144MHz，Dual／Triple Op Amps with $\pm 15 k V$ ESD Protection



Figure 1．Noninverting Gain Configuration


Figure 2．Inverting Gain Configuration
decrease bandwidth or cause oscillations．For exam－ ple，a noninverting gain－of－two configuration（ $R_{F}=R_{G}$ ） using $2 \mathrm{k} \Omega$ resistors，combined with 4 pF of amplifier input capacitance and 1 pF of PC board capacitance， cause a pole at 79.6 MHz ．Since this pole is within the amplifier bandwidth，it jeopardizes stability．Reducing the $2 k \Omega$ resistors to $100 \Omega$ extends the pole frequency to 1.59 GHz ，but could limit output swing by adding $200 \Omega$ in parallel with the amplifier＇s load resistor （Figures 1 and 2）．

## Layout and Power－Supply Bypassing

These amplifiers operate from a single 5V power sup－ ply．Bypass VCC to ground with a $0.1 \mu \mathrm{~F}$ capacitor as close to VCC as possible．Maxim recommends using microstrip and stripline techniques to obtain full band－ width．To ensure that the PC board does not degrade the amplifier＇s performance，design it for a frequency greater than 1 GHz ．Pay careful attention to inputs and outputs to avoid large parasitic capacitance．Under all conditions observe the following design guidelines：
－Do not use wire－wrap boards．Wire－wrap boards are too inductive．
－Do not use IC sockets．Sockets increase parasitic capacitance and inductance．
－Use surface mount instead of through－hole compo－ nents for better high－frequency performance．
－Use a PC board with at least two layers．The PC board should be as free from voids as possible．
－Keep signal lines as short and as straight as possi－ ble．Do not make $90^{\circ}$ turns；round all corners．

Output Capacitive Loading and Stability The MAX4030E／MAX4031E are optimized for AC perfor－ mance and do not drive highly reactive loads，which decreases phase margin and can produce excessive ringing and oscillation．Figure 3 shows a circuit modifi－ cation that uses an isolation resistor（RISO）to eliminate this problem．Figure 4 shows a graph of the Optimal Isolation Resistor（RISO）vs．Capacitive Load．Figure 5 shows how a capacitive load causes excessive peak－ ing of the amplifier＇s frequency response if the capaci－ tor is not isolated from the amplifier by a resistor．A small isolation resistor（usually $10 \Omega$ to $15 \Omega$ ）placed before the reactive load prevents ringing and oscilla－ tion．At higher capacitive loads，the interaction of the load capacitance and the isolation resistor controls the AC performance．Figure 6 shows the effect of a $10 \Omega$ isolation resistor on closed－loop response．

## ESD Protection

As with all Maxim devices，ESD protection structures are incorporated on all pins to protect against ESD encountered during handling and assembly．Input and output pins of the MAX4030E／MAX4031E have extra protection against static electricity．Maxim＇s engineers have developed state－of－the－art structures enabling these pins to withstand ESD up to $\pm 15 \mathrm{kV}$ without dam－ age when placed in the test circuit（Figure 7）．The MAX4030E／MAX4031E are characterized for protection to the following limits：
－$\pm 15 \mathrm{kV}$ using the Human Body Model
－$\quad \pm 8 \mathrm{kV}$ using the Contact Discharge method speci－ fied in IEC 1000－4－2
－$\pm 15 \mathrm{kV}$ using the Air－Gap Discharge method speci－ fied in IEC 1000－4－2


Figure 3．Driving a Capacitive Load Through an Isolation Resistor

## Low-Cost, 144MHz, Dual/Triple Op Amps with $\pm 15 k V$ ESD Protection



Figure 4. Isolation Resistance vs. Capacitive Load


Figure 5. Small-Signal Gain vs. Frequency with Load Capacitance and No Isolation Resistor

## Human Body Model

Figure 8 shows the Human Body Model and Figure 9 shows the current waveform it generates when discharged into low impedance. This model consists of a 150 pF capacitor charged to the ESD voltage of interest, and then discharged into the test device through a $1.5 \mathrm{k} \Omega$ resistor.


Figure 6. Small-Signal Gain vs. Frequency with Load Capacitance and $10 \Omega$ Isolation Resistor

IEC 1000-4-2
The IEC 1000-4-2 standard covers ESD testing and performance of finished equipment; it does not specifically refer to ICs. The MAX4030E/MAX4031E enable the design of equipment that meets the highest level (level 4) of IEC 1000-4-2 without the need for additional ESD protection components. The major difference between tests done using the Human Body Model and IEC 1000-$4-2$ is higher peak current in IEC 1000-4-2. Because series resistance is lower in the IEC 1000-4-2 model, the ESD-withstand voltage measured to this standard is generally lower than that measured using the Human Body. Figure 10 shows the IEC 1000-4-2 model and Figure 11 shows the current waveform for the $\pm 8 \mathrm{kV}$ IEC 1000-4-2 level 4 ESD Contact Discharge test. The Air-Gap test involves approaching the device with a charged probe. The Contact Discharge method connects the probe to the device before the probe is energized.

PROCESS: BiCMOS

## Low-Cost, 144MHz, Dual/Triple Op Amps with $\pm 15 k V$ ESD Protection



Figure 7. ESD Test Circuit

Figure 8. Human Body ESD Model



Figure 10. IEC 1000-4-2 ESD Test Model


Figure 11. IEC 1000-4-2 ESD Generator Current Waveform


- 11. IEC 1000-2-2 ESD Generarort


## Low-Cost, 144MHz, Dual/Triple Op Amps with $\pm 15 k V$ ESD Protection

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information, go to www.maxim-ic.com/packages.)


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